Microrredes Eléctricas



Distributed Energy Resources

- 1. PV Systems.
- 2. WT Generation
- 3. Battery Based Energy Storage Systems





Clasification by number of Power Stages



Single Stage Inverter



Two Stage Inverter



Multi String Inverter

Transformer based

Figures from [1]



Transformerless



Low Frequency Transformer



High Frequency Transformer



General Structure of a PV Inverter.







Model of a PV panel, and a PV panel Array.





Hands-on 1: Model of a PV Panel.



Explicit model proposed in [2].

$$V = V_{oc}(T,G) \left(1 - \frac{I}{I_{sc}(T,G)}\right)^{1/s}$$





Hands-on 1 Model of a PV Panel.

KuDymond CS3U-335|340|345P-FG



Simulation1 File.

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spectrum AM 1.5, ambient temperature 20°C, wind speed 1 m/s

Hands on Simulation 2.



Simulation2 File.



Hands-on PV panel connected to a load. I-V Curve Transducers Current (A) Irradiance MPPT Conductance of the load Adjustable PV panel Load 10 15 20 25 30 35 40 Voltage (V)





DC/DC Converters Topologies.



Buck



Hands-on Simulation 3.



Simulation3 File.



Hands-on Simulation 4.



Simulation4 File.



General Structure of a Typical PV Inverter.





Hands-on Simulation 4B.





Simulation4B File.

Maximum Power Point Tracking





Maximum Power Point Tracking MPPT



Seeking Algorithms Perturbation and Observation (P&O)



$- P(V)_{T_a=25,G=100}$	$\Delta mp = (38.01)$, 33.74)	$\rightarrow P(V)_{T_a=25,G=200}$	Omp=(38.49, 68.34)
$- P(V)_{T_a=25,G=500}$	mp=(39.13	, 173.69)	$ P(V)_{T_a=25,G=800}$	↓ mp=(39.47, 280.30)
$- P(V)_{T_a=25,G=1000}$	_mp=(39.63	, 351.86)	$\rightarrow P(V)_{T_a=25,G=1500}$	$0 \longrightarrow mp = (39.95, 532.08)$



Maximum Power Point Tracking



Fractional Open-Circuit Voltage (FOCV) Technique In this technique, can be calculated from the empirical relationship

 $V_{PMP} = kV_{oc}; k < 1$

The value of k varies between 0.78 and 0.92.



Maximum Power Point Tracking



Fractional Short-Circuit Current (FSCI) Technique In this technique, can be calculated from the empirical relationship

 $I_{PMP} = kI_{SC}; k < 1$

The value of k varies between 0.8 and 0.96

More details in [3]



Hands-on Simulation.



Simulation5 File.

General Structure of a PV Inverter. (DC/AC Side)





Typical Trasformer based PV Inverter Structures.

H-Bridge Based Boosting PV Inverter with Low-Frequency Transformer



H-Bridge Based Boosting PV Inverter with High-Frequency Transformer









PV

ф

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g X SW2

g 🔪 SW5

Hands-on Simulation Complete Grid Connected PV System.





Simulation8B File.

Simulation10 File.

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[3]. B. Subudhi and R. Pradhan, "A Comparative Study on Maximum Power Point Tracking Techniques for Photovoltaic Power Systems," in IEEE Transactions on Sustainable Energy, vol. 4, no. 1, pp. 89-98, Jan. 2013, doi: 10.1109/TSTE.2012.2202294.

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[5]. Remus Teodorescu; Marco Liserre; Pedro Rodriguez, "Grid Converters for Photovoltaic and Wind Power Systems" in Wiley-IEEE Press, 2007, pp.i-xvii, doi: 10.1002/9780470667057.fmatter.

[6]. I. - S. Kim, M. - B. Kim and M. - J. Youn, "New Maximum Power Point Tracker Using Sliding-Mode Observer for Estimation of Solar Array Current in the Grid-Connected Photovoltaic System," in IEEE Transactions on Industrial Electronics, vol. 53, no. 4, pp. 1027-1035, June 2006, doi: 10.1109/TIE.2006.878331.



3. Battery Based Energy Storage Systems



Why do we need energy storage for renewable energy?







High Power Density (**HPD**) Devices.

- Supercapacitors.
- Flywheels.
- SMES.

High Energy Density (**HED**) Devices.

• Batteries

$$P_{ESS} = P_{HPD} + P_{HED}$$



3. ESS

Power Density

Is the amount of **power** (time rate of energy transfer) per unit **volume**. expressed as (W/L, W/m³).

• Energy Density

Is the amount of **energy** stored in a given system or region of space per unit **volume**. expressed as (Wh/L, Wh/m³)





Comparison between Energy Storage Devices



Battery and Supercapacitor.



Low internal cell resistance is the key to high-rate capability.



Battery and Supercapacitor





Battery



	Charge Cut-off	Cell Voltage	Discharge Cut-off
	Voltage	Nominal	Voltage
Lead-acid	2.4 V	2 V	1.75 V
Li-Ion	4.20 V	4 ⁻ V	2.5-3.0 V



3. ESS Battery Model

Model Requirements.

- Consider internal resistance, such that under load conditions, the voltage increases, and under discharge conditions, the voltage decreases.
- Generate voltage variation curves based on the state of charge.
- Replicate dynamics in response to variations in load current.




3. ESS



 $V[SoC(t)] = a_0 e^{-a_1 SoC(t)} + a_2 + a_3 SoC(t) - a_4 SoC(t)^2 + a_4 SoC(t)^3$

Taesic Kim, and Wei Qiao, "A Hybrid Battery Model Capable of Capturing Dynamic Circuit Characteristics and Nonlinear Capacity Effects"

Min Chen, and Gabriel A. Rincón-Mora, "Accurate Electrical Battery Model Capable of Predicting Runtime and I-V Performance "



3. ESS SOC

$$SoC(\Delta t)_{Bat(i)} = SoC(0)_{Bat(i)} - \int_{0}^{\Delta t} \eta_{Bat(i)} \frac{I_{Bat(i)}(\tau)}{C_{Bat(i)}} d\tau;$$







This dynamics can be approximated by circuits using one or more subcircuits of resistors in parallel with capacitors.



This model is known as the Second Order Randles Model.





Electrical Model $NR_{series} NR_{trasient-fast} NR_{trasient-slow}$ $MR_{series} NR_{trasient-fast} NR_{trasient-slow}$ $MR_{trasient-fast} NR_{trasient-slow}$



1. PV Systems

General Structure of a Autonomous PV Inverter.



Simulation6 File.





General Scheme for WT Generation





Wind Power

Kinetic Energy





v = velocidad (m/s)



Wind Powe

Wind moves horizontaly The mass *m* of the wind can be dh=0. The Energy that can be estimated by the product of its $E_k = \frac{1}{2}\rho Vol * V^2$ extracted from wind is Kinetic density p and volume Vol Energy $m = \rho Vol$ $E_k = \frac{1}{2}mV^2$ $\Delta E_k = \frac{1}{2} \cdot \rho \cdot A \cdot \Delta L \cdot v^2$ A Δt At $E_{k} = \frac{1}{2} \cdot \rho \cdot A \cdot L \cdot v^{2}$ $P_0 = \frac{1}{2} \rho A v^3$ $A = area (m^2)$ $P_n = potencia del viento (W)$ L-longitud (m) © 1998 www.WINDPOWER.org



Generated Power.

In 1918 the German physicist Albert Betz published a theory in which he showed that the maximum kinetic energy extractable from the wind by a wind turbine is equal to 16/27 (59.26%).





Generated Power.

Betz Limit





Generated Power.

No rotor operates with a mechanical efficiency of 100%, so the Betz limit indicates the maximum extractable power, but in reality the power will be the result of the efficiency multiplied by the Betz limit, this factor is the power coefficient.





b://www.reysapo.com.uy/vientos-termicos-brisas-marinas/Facultad de Ingenie/waw.bvsde.paho.org/cursoa_meteoro/lecc3/lecc3_7.html











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2. WT Generation



Clasification based on the Machine

- Syncrhonous Machine
 - Permanent Magnet Generator(PMG).
 - Externaly exited (Sync Generator).
 - Multipole.
- Asyncrhonous (Induction).
 - Wound rotor Induction generator(WRIG).
 - Squirrel cage induction generator (SCIG).



Clasification based on Machine and Convertion Processes

- Type (A)
 - (Fixed Speed FS-WT).
- Type (B)
 - Limited Variable Speed.
- Type (C)
 - Variable Speed. (IM)
- Type (D)
 - Variable Speed. (SM)



(Type A) Fixed Speed WTG



• To operate as a Generator, it must ensure speeds greater than the synchronous speed.







(Type A) Fixed Speed WTG





Type A Fixed Speed WTG



Advantages.

- Economic.
- Robust.

Disadvantages

- It requires a strong and stable network.
- Requires gear box and/or multi-pole motor.
- It consumes reactive power.

- Commonly use SCIG.It
- requires a capacitor bank to compensate the reactive power consumed by the machine.
- Speeds higher than the synchronous speed must be ensured on the highspeed axis.
- It requires the network to magnetize and start.
- Requires an electronic drive circuit for soft start



Type (B) Limited Variable Speed WTG



Advantages.

- Variable speed up to +10% of the synchronous speed..
 Disadvantages.
- Losses
- Maintenance.
- It consumes reactive power.

- Use WRIG.
- It requires a capacitor bank to compensate the reactive power consumed by the machine.
- Speeds higher than the synchronous speed must be ensured on the high-speed axis.
- It requires the network to magnetize and start.
- Requires an electronic drive circuit for soft start.
- It uses variable resistors connected to the rotor circuit.
- Requires gearbox



(Type B) Limited Variable Speed WTG



(Type C) Doubly-Fed Wound Inductor Generator





(Type C) Doubly-Fed Wound Induction Generator





(Type C) Doubly-Fed Wound Induction Generator





(Tipo C) Doubly-Fed Wound Induction Generator. (Variable Speed)



Advantages.

- Smooth control of reactive power.
- It allows speed variations of up to 30% of the synchronous speed.
- Better efficiency as both rotor and generator can provide power

Disadvantages

- It requires high maintenance.
- Depends on the reliability of the

converter

- Use WRIG.
- It uses an AC/DC-DC/AC double conversion stage connected to the rotor terminals.
- Speeds higher than the synchronous speed must be ensured on the high-speed axis.
- It requires the network to magnetize and start.
- It does not require a drive circuit with the network.
- Decoupling in the control of active and reactive power (rotor current).

(Type D) Variable Speed.



Advantages.

 Full speed control.Frequency mismatch.Independent control of P/Q.

Disadvantages

- Higher cost.
- No inertia.

- Use WRIG, SCIG, SG, PMSG.
- It uses an AC/DC-DC/AC double conversion stage as the interface between grid and stator.
- Generates active or reactive power flow decoupling.
- The sync speed can be adjusted.
- It requires the network to magnetize and start.
- Variable speed in a wide range.
- It does not require a connection box or multipole motor.



Seguimiento de MPPT.



Type C&D

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(Type D) Variable Speed.









(Tipe D) Variable Speed.

Wind turbine control structure:





TRS (Tip Speed Ratio)

• **TRS (Tip-Speed ratio)**. Es la relación de la velocidad en punta de pala y la velocidad de viento incidente.

 $\lambda = \omega_r R / v_w$

• **Cp** Depende directamente del TRS y de el ángulo de paso (Pitch)



 $P_m = 0.5\pi\rho C_p(\lambda,\beta)R^2 v_w^3$


2. WT Generation

MPPT



 La potencia de una determinada turbina es máxima en cierto valor de velocidad de rotor llamado Velocidad Optima de Rotor.

$$\omega_{opt} = \frac{\lambda_{opt} v_w}{R}$$

Esta velocidad corresponde a un valor optimo del TRS. Entonces a este valor debe operar la turbina para asegurar MPPT.



2. WT Generation

MPPT





MPPT





MPPT





2. WT Generation

Modelling of the Wind Turbine Generation.



optimal generation curve.



Convertion Stage





Convertion Stage

Back to Back



Power Control loop.

DC Voltage control loop.



Simulation10 File.